

Numerical computations for the Calderón problem

Part 1

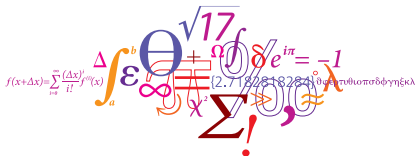
Kim Knudsen
Department of Mathematics
Technical University of Denmark
k.knudsen@mat.dtu.dk



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Outline

1. The Calderón problem
2. Calderón's linear reconstruction algorithm
3. The direct, non-linear reconstruction algorithm in 2D
4. Solution in 2D - regularized Dbar method
5. Conclusions



Collaborators

Jutta Bikowski, Agrosphere, Forschungszentrum Jülich, Germany

Horia Cornean, Aalborg University, Denmark

Fabrice Delbary, Technical University of Denmark

Per Christian Hansen, Technical University of Denmark

Matti Lassas, University of Helsinki, Finland

Jennifer Mueller, Colorado State University, Fort Collins, USA

Samuli Siltanen, University of Helsinki, Finland

1. The Calderón problem

The conductivity equation

Smooth bounded domain $\Omega \subset \mathbb{R}^n$, $n = 2, 3$; conductivity coefficient $\gamma \in L^\infty(\Omega)$, $C^{-1} \leq \text{Re}(\gamma)$, for $C > 0$.

A voltage potential u in Ω generated by Dirichlet data f

$$\nabla \cdot \gamma \nabla u = 0 \text{ in } \Omega.$$

$$f = u|_{\partial\Omega}$$

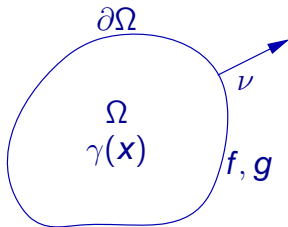
Corresponding Neumann data:

$$g = \gamma \partial_\nu u|_{\partial\Omega}.$$

Dirichlet to Neumann map

$$\Lambda_\gamma: H^{1/2}(\partial\Omega) \rightarrow H^{-1/2}(\partial\Omega)$$

$$f \mapsto g.$$



Inverse problem

Consider the (non-linear) mapping

$$\Lambda: \gamma \mapsto \Lambda_\gamma.$$

Conductivity \rightarrow Boundary measurements

This mapping encodes the direct problem.

The **Calderón problem** (the inverse conductivity problem):

- Uniqueness: is Λ injective?
- Reconstruction: how can γ be computed from Λ_γ ?

Data for inverse problem contains infinitely many measurements with infinite precision.

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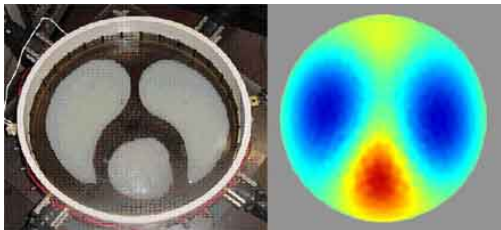
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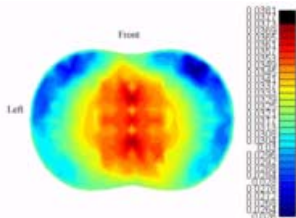
Applications include Electrical Impedance Tomography, emerging technology for medical imaging.

Electrical Impedance Tomography

Tank experiment:



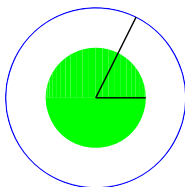
Clinical experiment



Most simple example

Suppose $\Omega = \mathbb{D} \subset \mathbb{R}^2$ and let

$$\gamma(\mathbf{x}) = \begin{cases} \gamma_0 & |\mathbf{x}| \leq r_0 \\ 1 & r_0 < |\mathbf{x}| \leq 1. \end{cases}$$



Then one can show that

$$\Lambda_\gamma(\mathbf{e}^{in\theta}) = \lambda_n \mathbf{e}^{in\theta},$$

with

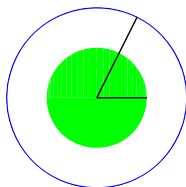
$$\lambda_n = |n| - \delta\lambda_n, \quad \delta\lambda_n = 2|n| \frac{1}{1 + \frac{1+\gamma_0}{1-\gamma_0} r_0^{-2|n|}}.$$

Inverse problem: Given Λ_γ or equivalently $\{\lambda_n\}$, find γ .

Most simple example

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Inverse problem: Given Λ_γ or equivalently $\{\lambda_n\}$, find γ .

Non-linear, severely ill-posed, inverse problem

Short and incomplete history

1980 Calderón: Problem posed, uniqueness for linearized problem, and linear, approximate reconstruction algorithm

3D

- 1987 Sylvester and Uhlmann: Uniqueness for smooth conductivities. Implicit reconstruction algorithm
1987-88 Novikov, Nachman-Sylvester-Uhlmann, Nachman: Uniqueness for conductivities with 2 derivatives and explicit high frequency reconstruction algorithm. Multidimensional D-bar equation.
1990 Alessandrini: Stability
2003 Brown-Torres, Päivärinta-Panchenko-Uhlmann: Uniqueness for conductivities with 3/2 derivatives.
2006 Cornean-Knudsen-Siltanen: Low frequency reconstruction algorithm
2010 Bikowski-Knudsen-Mueller: Numerical implementation of simplified reconstruction algorithm
2011 Debary - Hansen- Knudsen: Implementation of more accurate numerical reconstruction method

2D

- 1996 Nachman: Uniqueness and reconstruction for $W^{2,p}(\Omega)$ conductivities.
1997 Liu: Stability for $W^{2,p}(\Omega)$ conductivities
1997 Brown-Torres: Uniqueness for $W^{1,p}(\Omega)$ conductivities
2001 Barceló-Barceló-Ruiz: Stability for $C^{1+\epsilon}$ conductivities
2001 Knudsen-Tamasan: Reconstruction for $C^{1+\epsilon}$ conductivities
2005 Astala-Päivärinta: Uniqueness and reconstruction for $L^\infty(\Omega)$
2009 Knudsen-Lassas-Mueller-Siltanen: Regularized $\bar{\partial}$ -method
2010 Clop-Faraco-Ruiz: Stability for discontinuous conductivities

+ many more

Reconstruction methods

The reconstruction algorithms for the general Calderón problem can roughly be characterized:

1. **Linearization methods**
2. Optimization methods
3. Statistical methods
4. **Direct methods**

Reconstruction methods

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1. **Linearization methods**
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4. **Direct methods**

Other qualitative methods include:

- the probe method
- the linear sampling method
- the factorization method

Assumptions

Assume throughout that

1. Ω and γ are sufficiently smooth
2. $\gamma = 1$ near $\partial\Omega$
3. γ is extended to $\mathbb{R}^n \setminus \Omega$ by $\gamma = 1$
4. In 2D assume γ is real

Note that 1. and 4. are restrictive, but 2.-3. can be assumed WLOG.

2. Calderón's linear reconstruction algorithm

Calderón's reconstruction method

Linearize the mapping $\Lambda: \gamma \mapsto \Lambda_\gamma$, i.e. write

$$\Lambda_\gamma - \Lambda_1 \approx d\Lambda(\gamma - 1).$$

Integration by parts

$$\begin{aligned} \langle (\Lambda_\gamma - \Lambda_1)f, h \rangle &= \int_{\partial\Omega} (\Lambda_\gamma - \Lambda_1)f \, h dS \\ &= \int_{\Omega} (\gamma - 1) \nabla u \cdot \nabla v \, dx, \end{aligned}$$

where

$$\nabla \cdot \gamma \nabla u = 0, \quad u|_{\partial\Omega} = f, \quad \Delta v = 0, \quad v|_{\partial\Omega} = h.$$

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where

$$\nabla \cdot \gamma \nabla u = 0, \quad u|_{\partial\Omega} = f, \quad \Delta v = 0, \quad v|_{\partial\Omega} = h.$$

Then it turns out

$$\langle d\Lambda(\gamma - 1)f, h \rangle = \int_{\Omega} (\gamma - 1) \nabla u \cdot \nabla v \, dx,$$

where

$$\Delta u = 0, \quad u|_{\partial\Omega} = f, \quad \Delta v = 0, \quad v|_{\partial\Omega} = h.$$

Harmonic complex exponentials

To obtain information from the linearized equation take h, f as restrictions of harmonic functions

$$f = e^{ix \cdot \zeta}, \quad h = e^{-ix \cdot (\xi + \zeta)}$$

with $\xi \in \mathbb{R}^n$ and $\zeta = \zeta(\xi) \in \mathbb{C}^n$ s.t.

$$(\xi + \zeta)^2 = \zeta^2 = 0.$$

From Λ_γ we can compute the *near-field scattering transform* (non-linear in $\gamma - 1$)

$$\begin{aligned} \mathbf{t}^{\text{exp}}(\xi, \zeta) &= \left\langle (\Lambda_\gamma - \Lambda_1) e^{ix \cdot \zeta}, e^{-ix \cdot (\xi + \zeta)} \right\rangle \\ &= \int_{\Omega} (\gamma(\mathbf{x}) - 1) \nabla u^{\text{exp}}(\mathbf{x}, \zeta) \cdot \nabla e^{-ix \cdot (\xi + \zeta)} d\mathbf{x}, \end{aligned}$$

with

$$\nabla \cdot \gamma \nabla u^{\text{exp}} = 0 \text{ in } \Omega, u^{\text{exp}}|_{\partial\Omega} = e^{ix \cdot \zeta}.$$

Linear approximation

Writing $u^{\text{exp}} = e^{ix \cdot \zeta} + \delta u$ yields

$$\mathbf{t}^{\text{exp}}(\xi, \zeta) = -\frac{|\xi|^2}{2} \int_{\Omega} (\gamma(\mathbf{x}) - 1) e^{-ix \cdot \xi} d\mathbf{x} + R(\xi, \zeta),$$

$$R(\xi, \zeta) = \int_{\Omega} (\gamma(\mathbf{x}) - 1) \nabla \delta u \cdot \nabla e^{-ix \cdot (\zeta + \xi)} d\mathbf{x}.$$

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The linear part:

$$\langle d\Lambda(\gamma - 1)f, h \rangle = -\frac{|\xi|^2}{2} \int_{\Omega} (\gamma(\mathbf{x}) - 1) e^{-ix \cdot \xi} d\mathbf{x}.$$

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The linear part:

$$\langle d\Lambda(\gamma - 1)f, h \rangle = -\frac{|\xi|^2}{2} \int_{\Omega} (\gamma(\mathbf{x}) - 1) e^{-ix \cdot \xi} d\mathbf{x}.$$

Estimates:

$$|R(\xi, \zeta)| \leq C \|\gamma - 1\|_{L^\infty(\Omega)}^2 (1 + |\zeta|)^2 e^{2R|\zeta|}, \quad \Omega \subset B_R$$

$$|R(\xi, \zeta)| = \mathcal{O}(|\xi|^2) \text{ for } \xi \text{ small.}$$

The reconstruction formula

Calderón approximation formula (with low pass filter):

$$\gamma^{\text{app}}(\mathbf{x}) = 1 - \frac{1}{2(2\pi)^n} \int \frac{\mathbf{t}^{\text{exp}}(\xi, \zeta)}{|\xi|^2} e^{i\mathbf{x} \cdot \xi} \chi_K(\xi) d\xi.$$

Solves the problem to first order. Estimate:

$$\begin{aligned} \|\gamma^{\text{app}}(\mathbf{x}) - \eta_\gamma * \gamma\|_{L^\infty} &\leq \|R(k)\hat{\eta}(k/\gamma)\|_{L^1(\mathbb{R}^2)} \\ &\leq C\|\gamma - 1\|_{L^\infty(\Omega)}^{1+\alpha} (\log(\|\gamma - 1\|_{L^\infty(\Omega)}))^2. \end{aligned}$$

Support theorem

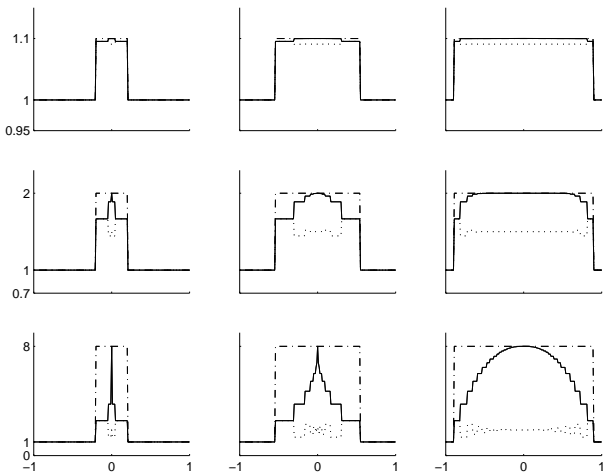
For the concentric inclusion in unit disk we obtain without filtering the linearized reconstruction

$$\gamma^{\text{app}}(\mathbf{x}) = 1 + 2\alpha \sum_{m=0}^{\infty} \alpha^m \chi_{r^{m+1}}(\mathbf{x})$$

with $\alpha = \frac{\sigma-1}{\sigma+1}$.

Special case of a recent support theorem obtained by von Harrach-Seo.

Calderón's method on concentric case



3. The direct, non-linear reconstruction algorithm in 2D

Transformation to Schrödinger equation

Suppose u solves

$$\nabla \cdot \gamma \nabla u = 0 \text{ in } \Omega, \quad u|_{\partial\Omega} = f.$$

Then $v = \gamma^{1/2}u$ solves

$$(-\Delta + q)v = 0 \text{ in } \Omega \quad v|_{\partial\Omega} = \gamma^{-1/2}f,$$

with $q = \Delta\gamma^{1/2}/\gamma^{1/2} \Leftrightarrow (-\Delta + q)\gamma^{1/2} = 0$.

Dirichlet to Neumann map

$$\Lambda_q f = \partial_\nu v.$$

If $\gamma = 1$ near $\partial\Omega$ then $\Lambda_q = \Lambda_\gamma$.

Complex geometrical optics (CGO)

Let $\zeta \in \mathbb{C}^n$ such that $\zeta \cdot \zeta = 0$. Look for a CGO solution ψ to the problem

$$\begin{aligned}(-\Delta + q)\psi(\mathbf{x}, \zeta) &= 0 \text{ in } \mathbb{R}^n, \\ \psi(\mathbf{x}, \zeta) &\sim e^{i\mathbf{x} \cdot \zeta} \text{ for large } |\mathbf{x}| \text{ or } |\zeta|.\end{aligned}$$

Lippmann-Schwinger-Faddeev (LSF) equation

$$\begin{aligned}\psi(\mathbf{x}, \zeta) &= e^{i\mathbf{x} \cdot \zeta} + \int_{\Omega} G_{\zeta}(\mathbf{x} - \mathbf{y})q(\mathbf{y})\psi(\mathbf{y}, \zeta)d\mathbf{x}, & -\Delta G_{\zeta} &= \delta_0, \\ & & G_{\zeta} &\sim e^{i\mathbf{x} \cdot \zeta}.\end{aligned}$$

CGO solutions in 2D

In 2D $\zeta \in \mathbb{C}^2$ with $\zeta \cdot \zeta = 0$ is parametrized by $\zeta = (k, \pm ik)$, $k \in \mathbb{C}$.
We will use complex notation $x = x_1 + ix_2$.
Equation for ψ or alternatively $\mu(x, k) = e^{ixk}\psi(x, k)$ is

$$4\bar{\partial}_x(\partial_x - ik)\mu + q\mu = 0.$$

Due to sharp estimates for ∂_x^{-1} (Vekua, 1962) one can obtain existence and uniqueness of CGO solutions for **all** $k \in \mathbb{C}$.

$\psi|_{\partial\Omega}$ at the boundary

Main Idea: use $\psi|_{\partial\Omega}$ as the boundary (voltage) fields

Suppose ζ is such that there is a unique CGO solution $\psi(\mathbf{x}, \zeta)$. Then $\psi|_{\partial\Omega}$ satisfies for fixed $\zeta \in \mathbb{C}^n$ the boundary integral equation

$$\psi(\mathbf{x}, \zeta) + \int_{\partial\Omega} \mathbf{G}_\zeta(\mathbf{x} - \mathbf{y})(\Lambda_\gamma - \Lambda_1)\psi(\mathbf{y}, \zeta) d\sigma(\mathbf{y}) = e^{i\mathbf{x} \cdot \zeta}, \quad \mathbf{x} \in \partial\Omega.$$

Written in terms of layer potentials

$$\psi + \mathbf{S}_\zeta(\Lambda_\gamma - \Lambda_1)\psi = e^{i\mathbf{x} \cdot \zeta}, \quad \mathbf{x} \in \partial\Omega.$$

This is a solvable Fredholm equation of the second kind.

$\psi|_{\partial\Omega}$ at the boundary

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This is a solvable Fredholm equation of the second kind.

Solving the equation is severely ill-posed!

Non-linear direct reconstruction algorithm

The key intermediate object, the *non-physical scattering transform*,

$$\begin{aligned}\mathbf{t}(\xi, \zeta) &= \int_{\partial\Omega} e^{-ix \cdot (\xi + \zeta)} (\Lambda_\gamma - \Lambda_1) \psi(\mathbf{x}, \zeta) |_{\partial\Omega} d\sigma, & (\xi + \zeta)^2 &= 0 \\ &= \int_{\Omega} e^{-ix \cdot (\xi + \zeta)} q(\mathbf{x}) \psi(\mathbf{x}, \zeta) dx.\end{aligned}$$

\mathbf{t} satisfies the estimate

$$|\hat{q}(\xi) - \mathbf{t}(\xi, \zeta)| = \mathcal{O}(1/|\zeta|).$$

Reconstruction algorithm

$$\Lambda_\gamma \rightarrow \mathbf{t}(\xi, \zeta) \rightarrow \gamma(\mathbf{x})$$

Second step depends on 2D or 3D.

Connection to Calderón reconstruction

Near-field scattering transform:

$$\begin{aligned} \mathbf{t}^{\text{exp}}(\xi, \zeta) &= \left\langle (\Lambda_\gamma - \Lambda_1) e^{ix \cdot \zeta}, e^{-ix \cdot (\zeta + \xi)} \right\rangle \\ &= \int_{\Omega} e^{-ix \cdot (\xi + \zeta)} q(x) v^{\text{exp}}(x, \zeta) dx, \end{aligned}$$

with $(-\Delta + q)v^{\text{exp}} = 0$ in Ω and $v^{\text{exp}}|_{\partial\Omega} = e^{ix \cdot \zeta}$.

Connection to Calderón reconstruction

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with $(-\Delta + q)v^{\text{exp}} = 0$ in Ω and $v^{\text{exp}}|_{\partial\Omega} = e^{ix \cdot \zeta}$.

Scattering transform:

$$\begin{aligned}\mathbf{t}(\xi, \zeta) &= \left\langle (\Lambda_\gamma - \Lambda_1)\psi, e^{-ix \cdot (\zeta + \xi)} \right\rangle \\ &= \int_{\Omega} e^{-ix \cdot (\xi + \zeta)} q(x) \psi(x, \zeta) dx,\end{aligned}$$

where $(-\Delta + q)\psi = 0$ in \mathbb{R}^n and $\psi \sim e^{ix \cdot \zeta}$ for x near ∞ .

4. Solution in 2D - the regularized Dbar-method

The Dbar reconstruction algorithm

1. Solve the boundary integral equation

$$\psi + \mathbf{S}_k(\Lambda_\gamma - \Lambda_1)\psi = e^{ixk}, \quad \mathbf{x} \in \partial\Omega,$$

and compute

$$\mathbf{t}(k) = \int_{\partial\Omega} e^{i\bar{k}\bar{\mathbf{x}}}(\Lambda_\gamma - \Lambda_1)\psi(\cdot, k)d\sigma.$$

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$$\mathbf{t}(k) = \int_{\partial\Omega} e^{i\bar{k}\bar{\mathbf{x}}}(\Lambda_\gamma - \Lambda_1)\psi(\cdot, k)d\sigma.$$

2. Evaluate $\gamma(\mathbf{x}) = \mu(\mathbf{x}, 0)^2$, where $\mu(\mathbf{x}, k) = e^{-ixk}\psi(\mathbf{x}, k)$ is found by solving the Dbar equation

$$\bar{\partial}_k \mu(\mathbf{x}, k) = \frac{1}{4\pi\bar{k}} \mathbf{t}(k) e_{-\mathbf{x}}(k) \overline{\mu(\mathbf{x}, k)}, \quad k \in \mathbb{C},$$

with $e_{-\mathbf{x}}(k) := e^{-i(k\mathbf{x} + \bar{k}\bar{\mathbf{x}})}$.

Provides a non-linear direct reconstruction algorithm for $\gamma \in \mathbf{C}^{1+\epsilon}(\bar{\gamma})$.

Regularization of the algorithm

In practice we measure Λ_γ with noise: $\tilde{\Lambda}_\gamma = \Lambda_\gamma + \mathcal{E}$

Problem: we don't know if $\tilde{\Lambda}_\gamma \in \text{range}(\Lambda)$, i.e. we don't know if there is $\tilde{\gamma}$ such that $\Lambda_{\tilde{\gamma}} = \tilde{\Lambda}_\gamma$.

This assumption is often made in stability estimates for the inverse problem.

Related to the notoriously difficult problem of the characterization of $\text{range}(\Lambda)$.

Non-linear regularization

Definition

A family of continuous mappings $\Gamma_\alpha : Y \rightarrow L^\infty(\Omega)$ parameterized by $0 < \alpha < \infty$ is a regularization strategy for F if

$$\lim_{\alpha \rightarrow 0} \|\Gamma_\alpha \Lambda_\gamma - \gamma\|_{L^\infty(\Omega)} = 0$$

for each fixed γ . Further, a regularization strategy with a choice $\alpha = \alpha(\varepsilon)$ of regularization parameter as function of noise level is called admissible if

$$\alpha(\varepsilon) \rightarrow 0 \text{ as } \varepsilon \rightarrow 0,$$

and for any fixed γ the following holds:

$$\sup_{\Lambda_\gamma^\varepsilon} \{ \|\Gamma_{\alpha(\varepsilon)} \Lambda_\gamma^\varepsilon - \gamma\|_{L^\infty(\Omega)} : \|\Lambda_\gamma^\varepsilon - \Lambda_\gamma\|_Y \leq \varepsilon \} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0.$$

Concrete strategy

Let $\alpha(\epsilon) = 1/R(\epsilon)$. Define $\Gamma_{\alpha(\epsilon)}\Lambda_\gamma$ by the steps

1. Solve

$$\tilde{\varphi}(\mathbf{z}, \mathbf{k}) = e^{i\mathbf{z}\mathbf{k}} - \mathbf{S}_k(\tilde{\Lambda}_\gamma - \Lambda_1)\tilde{\varphi}, \quad |\mathbf{k}| < R(\epsilon),$$

and

$$\tilde{\mathbf{t}}(\mathbf{k}) = \int_{\partial\Omega} e^{i\mathbf{z}\mathbf{k}} (\tilde{\Lambda}_\gamma - \Lambda_1)\tilde{\varphi}(\cdot, \mathbf{k}) d\sigma(\mathbf{z}). \quad |\mathbf{k}| < R(\epsilon)$$

2. Solve

$$\bar{\partial}_k \tilde{\mu}(\mathbf{x}, k) = \frac{1}{4\pi k} \tilde{\mathbf{t}}(\mathbf{k}) e_{-\mathbf{x}}(k) \overline{\tilde{\mu}(\mathbf{x}, k)}, \quad k \in \mathbb{C},$$

and compute $\Gamma_{\alpha(\epsilon)}\Lambda_\gamma = \tilde{\gamma}(\mathbf{x}) = (\tilde{\mu}(\mathbf{x}, 0))^2$.

Regularization theorem

Theorem

Suppose $\Lambda_\gamma^\varepsilon = \Lambda_\gamma + \mathcal{E}$ with $\|\mathcal{E}\| \leq \varepsilon < \varepsilon_0$. For $R(\varepsilon) = -\frac{1}{10} \log(\varepsilon)$, $\Gamma_{\alpha(\varepsilon)} \Lambda_\gamma$ is an admissible regularization strategy and

$$\|\Gamma_{\alpha(\varepsilon)} \Lambda_\gamma^\varepsilon - \gamma\|_{L^\infty(\Omega)} \leq C(-\log \varepsilon)^{-1/14}.$$

Regularization theorem

Theorem

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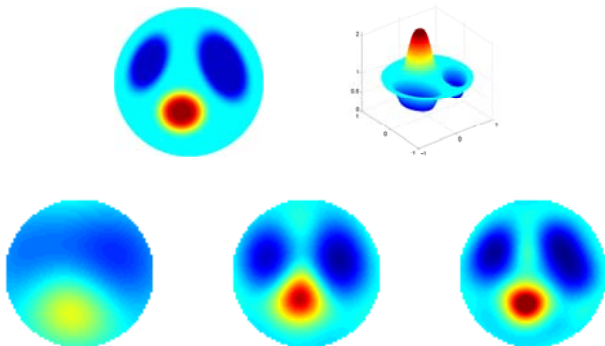
$$\|\Gamma_{\alpha(\varepsilon)} \Lambda_\gamma^\varepsilon - \gamma\|_{L^\infty(\Omega)} \leq C(-\log \varepsilon)^{-1/14}.$$

Note, we do not assume $\Lambda_\gamma^\varepsilon$ is in the range of Λ .

Implementation details

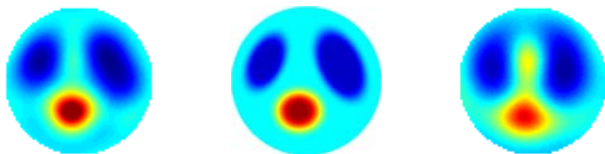
- Data simulated by solving forward problem by FEM
- Boundary integral equation is solved in Fourier basis and $\mathbf{t}(k)$ is computed using numerical integration
- Dbar equation solved as Lippmann-Schwinger integral equation using method of G. Vainikko

Numerical results



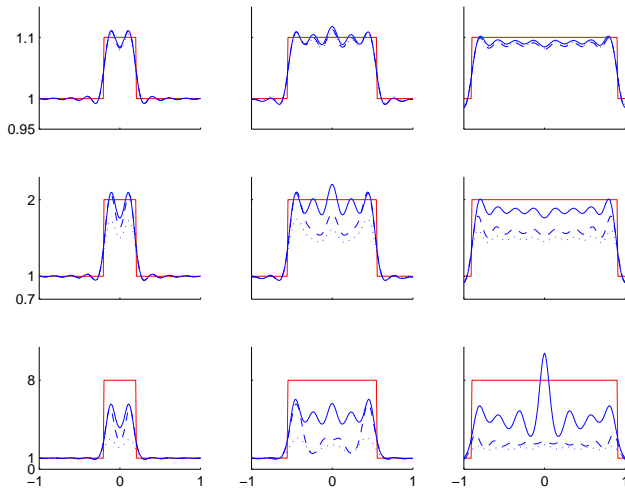
Reconstructions with noiselevel 10^{-2} , 10^{-4} and 10^{-6} . Error in approximation is 52%, 14% and 12% respectively.

Comparison to Calderón method



Reconstructions with noiselevel 10^{-6} . Left is non-linear direct reconstruction, right is reconstruction from Calderon method. Error in approximation is 12% and 23% respectively.

Reconstruction of non-smooth conductivities



Conclusion and outlook

- Presentation of Calderón's linearization algorithm
- Presentation of direct non-linear reconstruction algorithm in 2D
- Connection between the 2 established
- Implementation of linear reconstruction algorithm and non-linear method for computing conductivity.
- Rigorous regularization method in 2D
- Methods work reasonable well
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- The reconstruction problem with data measured only on part of the boundary

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Next (on Wednesday)

- The 3D problem: numerical solution of the forward problem and inverse problem

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Thank you