

# DRINFEL'D DOUBLES FOR (2+1)-POINCARÉ GRAVITY

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## Abstract

By starting from the complete classification of three-dimensional Lie bialgebra structures given in [1], all possible Drinfel'd double structures for the Poincaré algebra  $\mathfrak{iso}(2, 1)$  are constructed in a physically adapted basis. The corresponding classical r-matrices are given, together with the resulting pairing between basis generators. We explore the relations between the associated quantum Poincaré groups and (2+1) gravity with vanishing cosmological constant, where the former appear naturally as symmetries of the corresponding non-commutative spacetimes.

## 1 Quantum groups and Poisson-Lie groups in (2+1) gravity

Quantum group symmetries play an important role in the quantisation of gravity. They occur:

- In **Hamiltonian quantisation formalisms** such as combinatorial quantisation and in path integral approaches (state sum models, spin foams).
- In **phenomenological approaches** in three and higher dimensions, in **non-commutative geometry models** such as  $\kappa$ -Poincaré models and related 'doubly special relativity' theories.

For a given Lie algebra/group, there are **many possible quantum deformations**. In **(2+1)-gravity**, the classical counterpart of quantum groups (**Poisson-Lie groups**) arise naturally:

- Poisson-Lie (PL) structures on the isometry groups of (2+1) spaces with constant curvature play a relevant role as **phase spaces when (2+1) gravity is considered as a Chern-Simons (CS) gauge theory** [2, 3].
- These PL structures are given by certain **classical r-matrices** that **have to be 'compatible' with the CS formalism**, in the sense that the **symmetric component of r** has to be directly related with the Ad-invariant symmetric bilinear form in the CS action.

Therefore, it seems natural that the appropriate **quantum groups** in (2+1) gravity should be the **quantizations of these admissible r-matrices and PL symmetries**.

## 2 The (2+1) gravity $\leftrightarrow$ Drinfel'd double relation

But such admissible r-matrices have to be identified. As it has been shown in [4]:

All the classical r-matrices coming from a Drinfel'd double structure of the (2+1) Lorentzian isometry groups -(A)dS and Poincaré- fulfill the Fock-Rosly condition and are compatible with the CS formalism.

In this contribution we present in detail the results for the Poincaré case:

- We give the **5 possible Drinfel'd double structures for the Poincaré** Lie algebra  $\mathfrak{iso}(2, 1)$ .
- We obtain **5 candidates for quantum deformations of the Poincaré symmetries** that would be appropriate in a (2+1)-gravity setting.
- The new **Poincaré non-commutative spacetimes** coming from such quantum groups should be relevant in the corresponding (2+1) quantum gravity theory.

## 3 The Poincaré isometry group and its Lie algebra

Any solution of the 3d vacuum Einstein equations is of **constant curvature** which **cosmological constant**  $\Lambda$  and is locally isometric to one of the **six standard spacetimes**:

$\Lambda > 0$	$\Lambda = 0$	$\Lambda < 0$
$\mathbf{dS}^{2+1} = SO(3, 1)/SO(2, 1)$ $\text{Isom}(\mathbf{dS}^{2+1}) = SO(3, 1)$	$\mathbf{M}^{2+1} = ISO(2, 1)/SO(2, 1)$ $\text{Isom}(\mathbf{M}^{2+1}) = ISO(2, 1)$	$\mathbf{AdS}^{2+1} = SO(2, 2)/SO(2, 1)$ $\text{Isom}(\mathbf{AdS}^{2+1}) = SO(2, 2)$
$\mathbf{S}^3 = SO(4)/SO(3)$ $\text{Isom}(\mathbf{S}^3) = SO(4)$	$\mathbf{E}^3 = ISO(3)/SO(3)$ $\text{Isom}(\mathbf{E}^3) = ISO(3)$	$\mathbf{H}^3 = SO(3, 1)/SO(3)$ $\text{Isom}(\mathbf{H}^3) = SO(3, 1)$

- **Euclidean signature**: the **three-sphere**  $\mathbf{S}^3$  ( $\Lambda > 0$ ), 3d **hyperbolic** space  $\mathbf{H}^3$  ( $\Lambda < 0$ ) and 3d **Euclidean** space  $\mathbf{E}^3$  ( $\Lambda = 0$ ).
- **Lorentzian signature**: the 3d **de Sitter** space  $\mathbf{dS}^{2+1}$  ( $\Lambda > 0$ ) [4], **Anti-de Sitter** space  $\mathbf{AdS}^{2+1}$  ( $\Lambda < 0$ ) [4] and **Minkowski** space  $\mathbf{M}^{2+1}$  ( $\Lambda = 0$ ) [6].

The **Lie algebra** of the **Poincaré isometry group of the (2+1) Minkowski spacetime** can be written in a **kinematical basis** in terms of generators  $J$  (**rotation**),  $K_1, K_2$  (**boosts**) and  $P_0, P_1, P_2$  (**translations**), where the latter commute.

The explicit commutation relations are:

$$\begin{aligned} [J, K_1] &= K_2, & [J, K_2] &= -K_1, & [K_1, K_2] &= -J, \\ [J, P_0] &= 0, & [J, P_1] &= P_2, & [J, P_2] &= -P_1, \\ [K_1, P_0] &= P_1, & [K_1, P_1] &= P_0, & [K_1, P_2] &= 0, \\ [K_2, P_0] &= P_2, & [K_2, P_1] &= 0, & [K_2, P_2] &= P_0, \\ [P_0, P_1] &= 0, & [P_0, P_2] &= 0, & [P_1, P_2] &= 0. \end{aligned} \quad (3.1)$$

We have **two quadratic Casimir elements** given by

$$\begin{aligned} C_1 &= P_0^2 - P_1^2 - P_2^2, \\ C_2 &= \frac{1}{2} (J P_0 + P_0 J + K_2 P_1 + P_1 K_2 - (K_1 P_2 + P_2 K_1)). \end{aligned}$$

and associated to the second one, **the following non-degenerate symmetric Ad-invariant bilinear form** which is the relevant one in (2+1)-gravity:

$$\langle J, P_0 \rangle_t = 1, \quad \langle K_1, P_2 \rangle_t = -1, \quad \langle K_2, P_1 \rangle_t = 1$$

## 4 Classical r-matrices from Drinfel'd doubles

**Definition** [5]: A **2d-dimensional Lie algebra**  $\mathfrak{a}$  has the structure of a (classical) Drinfel'd double if there exists a basis  $\{X_1, \dots, X_d, x^1, \dots, x^d\}$  of  $\mathfrak{a}$  in which the Lie bracket takes the form

$$[X_i, X_j] = c_{ij}^k X_k \quad [x^i, x^j] = f_k^{ij} x^k \quad [x^i, X_j] = c_{jk}^i x^k - f_j^{ik} X_k.$$

As a consequence:

- An **Ad-invariant symmetric bilinear form on**  $\mathfrak{a}$  is given by

$$\langle X_i, X_j \rangle = 0 \quad \langle x^i, x^j \rangle = 0 \quad \langle x^i, X_j \rangle = \delta_j^i \quad \forall i, j.$$

- A **quadratic Casimir operator for**  $\mathfrak{a}$  is always given by

$$C = \frac{1}{2} \sum_i (x^i X_i + X_i x^i).$$

- **If**  $\mathfrak{a}$  **is a DD Lie algebra, its corresponding Lie group can be always endowed with a PL structure** generated by the **canonical classical r-matrix**

$$r = \sum_i x^i \otimes X_i = \frac{1}{2} \sum_i x^i \wedge X_i + \frac{1}{2} \sum_i (x^i \otimes X_i + X_i \otimes x^i)$$

which is a (constant) solution of the Classical Yang-Baxter equation  $[[r, r]] = 0$ .

Since the **symmetric component of r** coincides with the **tensorized form of the canonical quadratic Casimir element in**  $\mathfrak{a}$ , then the **Fock-Rosly condition is automatically fulfilled**.

**Therefore, in (2+1)-Poincaré gravity, any DD structure on**  $so(2, 1) \ltimes \mathbb{R}^3$  **will provide an admissible r-matrix**.

## 5 Admissible Poincaré r-matrices from $so(2, 1) \ltimes \mathbb{R}^3$ DDs

The **complete classification of the six-dimensional DD Lie algebras is known** [1]. In particular, the **Poincaré Lie algebra**  $so(2, 1) \ltimes \mathbb{R}^3$  admits only **five DD structures** ( $\mathfrak{g}, \mathfrak{g}^*$ ):

1.  $(so(2, 1), \mathfrak{r}_3(1)) \equiv$  Case 3 from [1]
2.  $(\mathfrak{r}_3(1), \mathfrak{n}_3) \equiv$  Case 10 from [1]
3.  $(\mathfrak{r}_3'(1), \mathfrak{n}_3) \equiv$  Case 13 from [1]
4.  $(\mathfrak{r}_3'(1), \mathfrak{s}_3(0)) \equiv$  Case 14' from [1]
5.  $(\mathfrak{r}_3(-1), \mathfrak{r}_3'(1)) \equiv$  Case 14 from [1]

The corresponding **admissible r-matrices** coming from them are given below. In all cases we give the most general admissible r-matrix.

1.  $r_A' = \alpha_1 (J \wedge K_1 + K_2 \wedge K_1) + \beta_1 (P_0 \wedge J + K_1 \wedge P_2 + P_1 \wedge K_2)$
2.  $r_A' = \alpha_2 (P_0 \wedge K_2 + P_2 \wedge K_2) + \beta_2 (J \wedge P_2 + \frac{1}{2} (P_1 \wedge K_2 + J \wedge P_0 + K_1 \wedge P_2))$
3.  $r_A' = \alpha_3 (P_0 \wedge K_2 + P_2 \wedge K_2) - \beta_3 (J \wedge P_2 + \frac{1}{2} (P_1 \wedge K_2 + J \wedge P_0 + K_1 \wedge P_2)) + \delta_3 P_1 \wedge P_0 + \gamma_3 2 (P_2 \wedge P_0) + \epsilon_3 2 P_1 \wedge P_2$
4.  $r_A' = \alpha_4 (2 P_1 \wedge J + J \wedge P_0 + K_1 \wedge P_2 + P_1 \wedge K_2)$
5.  $r_A' = \alpha_5 (P_1 \wedge J + \frac{1}{2} (J \wedge P_0 + K_1 \wedge P_2 + P_1 \wedge K_2)) + \beta_5 P_0 \wedge P_1$

It is worth noting that the second and fourth r-matrices are just particular cases of the third and fifth ones, respectively. This fact will be translated to the resulting noncommutative space-times below.

## 6 Five noncommutative (2+1) Poincaré spacetimes

**These five admissible r-matrices give rise to five new quantum Poincaré groups, whose explicit construction is in progress** [6]. We present here the **expressions for the PL structure corresponding to these five cases**.

The Poisson brackets that define the PL structure on  $\mathcal{C}^\infty(ISO(2, 1))$  associated to a given classical r-matrix  $r = r^{ij} X_i \otimes X_j$  are given by the **Sklyanin bracket**

$$\{f, g\} = r^{ij} (X_i^L f X_j^L g - X_i^R f X_j^R g) \quad f, g \in \mathcal{C}^\infty(ISO(2, 1)).$$

Under a **suitable parametrization of the**  $ISO(2, 1)$  **group in terms of geodesic parallel coordinates**, and after computing the left and right invariant vector fields on it, the **Poisson-Lie brackets among the spacetime coordinates read** [6]

Case	$\{x_0, x_1\}$	$\{x_0, x_2\}$	$\{x_1, x_2\}$
1.	$-\alpha_1(x_0 x_2 + x_1 x_2) + 2\beta_1 x_2$	$\alpha_1(x_0 x_1 + x_1^2) - 2\beta_1 x_1$	$\alpha_1(x_0 x_1 + x_0^2) - 2\beta_1 x_0$
2.	0	$\alpha_2(-x_0 + x_2)$	$\beta_2(-x_0 + x_2)$
3.	$0 + f_1(\xi_1, \xi_2, \theta)$	$\alpha_3(-x_0 + x_2) + f_2(\xi_1, \xi_2, \theta)$	$\beta_3(-x_0 + x_2) + f_3(\xi_1, \xi_2, \theta)$
4.	0	0	$-2\alpha_4(x_0 + x_1)$
5.	$0 + f_4(\xi_1, \xi_2, \theta)$	$0 + f_5(\xi_1, \xi_2, \theta)$	$-2\alpha_5(x_0 + x_1) + f_6(\xi_1, \xi_2, \theta)$

Note that:

- The quantization of these algebras will give **new non-commutative Poincaré spacetimes**.
- As stated above, 2 and 4 are particular cases of 3 and 5, respectively. **The commutation relations for each case are recovered when the appropriate parameters vanish**.
- Cases 1, 2 and 4 present **commutation relations among spacetime coordinates where only these same coordinates appear**. This fact is in agreement with **the idea of a (physical) noncommutative spacetime**.

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