# *b*-Symplectic manifolds: going to infinity and coming back

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- 2  $b^n$ -Symplectic manifolds
- 3 Integrable systems on *b*-symplectic manifolds
- 4 Deblogging  $b^n$ -symplectic manifolds

## The restricted 3-body problem (joint with Delshams)

- Simplified version of the general 3-body problem. One of the bodies has negligible mass.
- The other two bodies move independently of it following Kepler's laws for the 2-body problem on elliptic orbits with eccentricity *e*.



#### Figure: Circular 3-body problem

## Planar restricted 3-body problem

• By Newton's law of universal gravitation

$$\frac{d^2q}{dt^2} = (1-\mu)\frac{q_1-q}{|q_1-q|^3} + \mu\frac{q_2-q}{|q_2-q|^3}$$
(1)

with  $q_1 = q_1(t)$  the position of the planet with mass  $1 - \mu$  at time t and  $q_2 = q_2(t)$  the position of the one with mass  $\mu$ .

- Introducing the momentum p = dq/dt and the time-dependent self-potential of the small body  $U(q,t) = \frac{1-\mu}{|q-q_1|} + \frac{\mu}{|q-q_2|}$ Equation (1) can be rewritten as a Hamiltonian system with Hamiltonian  $H(q,p,t) = p^2/2 U(q,t), \quad (q,p) \in \mathbf{R}^2 \times \mathbf{R}^2,$ .
- The primaries move around their center of mass on ellipses and it is useful to introduce polar coordinates for  $q = (X, Y) \in \mathbf{R}^2 \setminus \{0\}$ ,  $X = r \cos \alpha, Y = r \sin \alpha, \qquad (r, \alpha) \in \mathbf{R}^+ \times \mathbb{T}$
- The momenta  $p = (P_X, P_Y)$  are transformed in such a way that the total change of coordinates  $(X, Y, P_X, P_Y) \mapsto (r, \alpha, P_r =: y, P_\alpha =: G)$  is canonical, i.e. the symplectic structure remains the same.

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## Planar restricted 3-body problem

• To study the behaviour at  $r = \infty$ , we introduce McGehee coordinates  $(x, \alpha, y, G)$ , where

$$r = \frac{2}{x^2}, \quad x \in \mathbf{R}^+.$$

 This transformation is non-canonical i.e. the symplectic structure changes: for x > 0 it is given by

$$-\frac{4}{x^3}dx \wedge dy + d\alpha \wedge dG.$$

which extends to a  $b^3$ -symplectic structure on  $\mathbf{R} \times \mathbb{T} \times \mathbb{R}^2$ .

• The Poisson bracket is

$$\{f,g\} = -\frac{x^3}{4} \left(\frac{\partial f}{\partial g}\frac{\partial g}{\partial y} - \frac{\partial f}{\partial y}\frac{\partial g}{\partial x}\right) + \frac{\partial f}{\partial \alpha}\frac{\partial g}{\partial G} - \frac{\partial f}{\partial G}\frac{\partial g}{\partial \alpha}$$

• The integrable 2-body problem for  $\mu = 0$  is integrable with respect to the singular  $\omega$ .

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## Model for these systems

$$\omega = \frac{1}{\mathbf{x_1^n}} \mathbf{dx_1} \wedge \mathbf{dy_1} + \sum_{\mathbf{i} > \mathbf{2}} \mathbf{dx_i} \wedge \mathbf{dy_i}$$

Close to  $x_1 = 0$ , the systems behave like,



and not like,





## The 3-body problem

- Consider the system of three bodies with masses  $m_1, m_2, m_3$  and positions  $\mathbf{q_1} = (q_1, q_2, q_3), \mathbf{q_2} = (q_4, q_5, q_6), \mathbf{q_3} = (q_7, q_8, q_9) \in \mathbb{R}^3.$
- Define the  $9 \times 9$  matrix  $M := \text{diag}(m_1, m_1, m_1, m_2, m_2, m_3, m_3, m_3)$ .
- Assume central coordinates  $(m_1\mathbf{q_1} + m_2\mathbf{q_2} + m_3\mathbf{q_3} = 0)$ .
- Introduce the following "McGehee"-coordinates:

$$r := \sqrt{q^T M q}, \qquad s := \frac{q}{r}, \qquad z := p\sqrt{r}.$$
(2)

• r = 0 corresponds to triple collisions. Essentially, these are spherical coordinates since s lies on the unit-sphere in  $\mathbb{R}^9$  with respect to the metric given by M.

## The 3-body problem

• The standard symplectic form  $\sum_{i=1}^{9} dq_i \wedge dp_i$  becomes in the new coordinates  $(r, s_1, \ldots, s_8, z_1, \ldots, z_9)$ .

$$\sum_{i=1}^{8} \left( \frac{s_i}{\sqrt{r}} dr \wedge dz_i + \sqrt{r} ds_i \wedge dz_i - \frac{z_i}{2\sqrt{r}} ds_i \wedge dr \right) + \frac{1}{\sqrt{\overline{m}_9 r \mu}} \left( \mu dr \wedge dz_9 - r \sum_{i=1}^{8} \overline{m}_i s_i ds_i \wedge dz_9 + \frac{z_9}{2} \sum_{i=1}^{8} \overline{m}_i s_i ds_i \wedge dr \right),$$

with 
$$\mu := 1 - \sum_{i=1}^{8} s_i^2 \overline{m}_i$$
.

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$$\bigwedge_{i=1}^{9} dq_i \wedge dp_i = \sqrt{\frac{\mu r^7}{\overline{m}_9}} ds_1 \wedge dz_1 \wedge ds_2 \wedge dz_2 \wedge \ldots \wedge ds_8 \wedge dz_8 \wedge dr \wedge dz_9,$$

It is a  $\frac{7}{2}$ -folded symplectic structure. (In the *n*-body problem *m*-folded symplectic for a certain *m*).

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## Other examples

 Kustaanheimo-Stiefel regularization for *n*-body problem (useful for binary collisions) → folded-type symplectic structures with hyperbolic singularities



 two fixed-center problem via Appell's transformation → combination of folded-type and b<sup>m</sup>-symplectic structures → Dirac structures.

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b-Symplectic manifolds

#### Definition

Let  $(M^{2n},\Pi)$  be an (oriented) Poisson manifold such that the map

 $p \in M \mapsto (\Pi(p))^n \in \Lambda^{2n}(TM)$ 

is transverse to the zero section, then  $Z = \{p \in M | (\Pi(p))^n = 0\}$  is a hypersurface called *the critical hypersurface* and we say that  $\Pi$  is a **Poisson** *b*-structure on (M, Z).

#### Symplectic foliation of a *b*-Poisson manifold

The symplectic foliation has dense symplectic leaves and codimension 2 symplectic leaves whose union is Z.

#### Theorem (Guillemin-M.-Pires)

For all  $p \in Z$ , there exists a Darboux coordinate system  $x_1, y_1, \ldots, x_n, y_n$  centered at p such that Z is defined by  $x_1 = 0$  and

$$\Pi = x_1 \frac{\partial}{\partial x_1} \wedge \frac{\partial}{\partial y_1} + \sum_{i=2}^n \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial y_i}$$

#### Darboux for $b^n$ -symplectic structures

$$\Pi = x_1^n \frac{\partial}{\partial x_1} \wedge \frac{\partial}{\partial y_1} + \sum_{i=2}^n \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial y_i}$$

or dually

$$\omega = \frac{1}{x_1^n} dx_1 \wedge dy_1 + \sum_{i=2}^n dx_i \wedge dy_i$$

Radko classified b-Poisson structures on compact oriented surfaces:

- Geometrical invariants: The topology of S and the curves  $\gamma_i$  where  $\Pi$  vanishes.
- Dynamical invariants: The periods of the "modular vector field" along  $\gamma_i$ .
- Measure: The regularized Liouville volume of S,  $V_h^{\varepsilon}(\Pi) = \int_{|h|>\varepsilon} \omega_{\Pi}$  for h a function vanishing linearly on the curves  $\gamma_1, \ldots, \gamma_n$  and  $\omega_{\Pi}$  the "dual "form to the Poisson structure.

Other classification schemes: For  $b^n$ -symplectic structures (not necessarily oriented)  $\rightsquigarrow$  Scott, M.-Planas.



- The product of  $(R, \pi_R)$  a Radko compact surface with a compact symplectic manifold  $(S, \omega)$  is a *b*-Poisson manifold.
- corank 1 Poisson manifold  $(N, \pi)$  and X Poisson vector field  $\Rightarrow (S^1 \times N, f(\theta) \frac{\partial}{\partial \theta} \wedge X + \pi)$  is a *b*-Poisson manifold if,
  - f vanishes linearly.
  - 2 X is transverse to the symplectic leaves of N.

We then have as many copies of N as zeroes of f.

This last example is semilocally the *canonical* picture of a b-Poisson structure .

- The critical hypersurface Z has an induced regular Poisson structure of corank 1.
- There exists a Poisson vector field transverse to the symplectic foliation induced on Z.

#### Theorem (Guillemin-M.-Pires)

If  $\mathcal{L}$  contains a compact leaf L, then Z is the mapping torus of the symplectomorphism  $\phi : L \to L$  determined by the flow of a Poisson vector field v transverse to the symplectic foliation.



This description also works for  $b^n$ -symplectic structures.

## A dual approach...

- *b*-Poisson structures can be seen as symplectic structures modeled over a Lie algebroid (the b-tangent bundle).
- A vector field v is a *b*-vector field if  $v_p \in T_pZ$  for all  $p \in Z$ . The *b*-tangent bundle  ${}^bTM$  is defined by

$$\Gamma(U, {}^{b}TM) = \begin{cases} \text{b-vector fields} \\ \text{on } (U, U \cap Z) \end{cases}$$



• The *b*-cotangent bundle  ${}^{b}T^{*}M$  is  $({}^{b}TM)^{*}$ . Sections of  $\Lambda^{p}({}^{b}T^{*}M)$  are *b*-forms,  ${}^{b}\Omega^{p}(M)$ . The standard differential extends to

 $d: {}^{b}\Omega^{p}(M) \to {}^{b}\Omega^{p+1}(M)$ 

- A *b*-symplectic form is a closed, nondegenerate, *b*-form of degree 2.
- This dual point of view, allows to prove a *b*-Darboux theorem and semilocal forms via an adaptation of Moser's path method because we can play the same tricks as in the symplectic case.

#### What else?

## *b*-integrable systems

#### Definition

b-integrable system A set of b-functions  $f_1, \ldots, f_n$  on  $(M^{2n}, \omega)$  such that

- $f_1, \ldots, f_n$  Poisson commute.
- $df_1 \wedge \cdots \wedge df_n \neq 0$  as a section of  $\Lambda^n({}^bT^*(M))$  on a dense subset of M and on a dense subset of Z

 $c \log |x| + g$ 

#### Example

The symplectic form  $\frac{1}{h}dh \wedge d\theta$  defined on the interior of the upper hemisphere  $H_+$  of  $S^2$  extends to a *b*-symplectic form  $\omega$  on the double of  $H_+$  which is  $S^2$ . The triple  $(S^2, \omega, log|h|)$  is a *b*-integrable system.

#### Example

If  $(f_1, \ldots, f_n)$  is an integrable system on M, then  $(\log |h|, f_1, \ldots, f_n)$  on  $H_+ \times M$  extends to a *b*-integrable on  $S^2 \times M$ .

## Action-angle coordinates for b-integrable systems

The compact regular level sets of a *b*-integrable system are (Liouville) tori.

Theorem (Kiesenhofer-M.-Scott)

Around a Liouville torus there exist coordinates  $(p_1, \ldots, p_n, \theta_1, \ldots, \theta_n) : U \to B^n \times \mathbf{T}^n$  such that

$$\omega|_{U} = \frac{c}{p_{1}}dp_{1} \wedge d\theta_{1} + \sum_{i=2}^{n} dp_{i} \wedge d\theta_{i},$$
(3)

and the level sets of the coordinates  $p_1, \ldots, p_n$  correspond to the Liouville tori of the system.

#### Reformulation of the result

Integrable systems semilocally  $\iff$  twisted cotangent lift<sup>a</sup> of a  $\mathbb{T}^n$  action by translations on itself to  $(T^*\mathbb{T}^n)$ .

<sup>a</sup>We replace the Liouville form by  $c \log |p_1| d\theta_1 + \sum_{i=2}^n p_i d\theta_i$ .

### Intermezzo on twisted b-cotangent lifts

Consider  $G := S^1 \times \mathbf{R}^+ \times S^1$  acting on  $M := S^1 \times \mathbf{R}^2$ :

 $(\varphi, a, \alpha) \cdot (\theta, x_1, x_2) := (\theta + \varphi, aR_{\alpha}(x_1, x_2)), \text{ with } R_{\alpha} \text{ rotation.}$ 

Its twisted b-cotangent lift gives focus-focus singularities on b-symplectic manifolds.

The logarithmic Liouville one-form is  $\lambda:=\log|p|d\theta+y_1dx_1+y_2dx_2$  and the moment map is  $\mu:=(f_1,f_2,f_3)$  with

$$f_1 = \langle \lambda, X_1^{\#} \rangle = \log |p|,$$
  

$$f_2 = \langle \lambda, X_2^{\#} \rangle = x_1 y_1 + x_2 y_2,$$
  

$$f_3 = \langle \lambda, X_3^{\#} \rangle = x_1 y_2 - y_1 x_2.$$



- Topology of the foliation. In a neighbourhood of a compact connected fiber the b-integrable system F is diffeomorphic to the b-integrable system on W := T<sup>n</sup> × B<sup>n</sup> given by the projections p<sub>1</sub>,..., p<sub>n-1</sub> and log |p<sub>n</sub>|.
- Output Description of periods: We want to define integrals whose (b-)Hamiltonian vector fields induce a T<sup>n</sup> action. Start with R<sup>n</sup>-action:

$$\begin{aligned} \Phi &: \mathbf{R}^n \times (\mathbf{T}^n \times B^n) &\to \mathbf{T}^n \times B^n \\ & ((t_1, \dots, t_n), m) &\mapsto \Phi_{t_1}^{(1)} \circ \dots \circ \Phi_{t_n}^{(n)}(m). \end{aligned}$$

Uniformize to get a  $\mathbf{T}^n$  action with fundamental vector fields  $Y_i$ .

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- Topology of the foliation. In a neighbourhood of a compact connected fiber the b-integrable system F is diffeomorphic to the b-integrable system on W := T<sup>n</sup> × B<sup>n</sup> given by the projections p<sub>1</sub>,..., p<sub>n-1</sub> and log |p<sub>n</sub>|.
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Uniformize to get a  $\mathbf{T}^n$  action with fundamental vector fields  $Y_i$ .

- So The vector fields  $Y_i$  are Poisson vector fields (check  $\mathcal{L}_{Y_i}\mathcal{L}_{Y_i}\omega = 0$ ).
- The vector fields Y<sub>i</sub> are Hamiltonian with primitives σ<sub>1</sub>,..., σ<sub>n</sub> ∈<sup>b</sup>C<sup>∞</sup>(W). In this step the properties of b-cohomology are essential. Use this action to drag a local normal form (Darboux-Carathéodory) in a whole neighbourhood.



Figure: Fibration by Liouville tori

Applications to KAM theory (surviving torus under perturbations ) on *b*-symplectic manifolds (Kiesenhofer-M.-Scott).

#### Theorem (Kiesenhofer-M.-Scott)

Consider  $\mathbf{T}^n \times B_r^n$  with the standard *b*-symplectic structure and consider the *b*-function  $H = k \log |y_1| + h(y)$  with *h* analytic. If the frequency map has a Diophantine value and is non-degenerate, then a Liouville torus on *Z* persists under sufficiently small perturbations of *H*. More precisely, if  $|\epsilon|$  is sufficiently small, then the perturbed system

 $H_{\epsilon} = H + \epsilon P$ 

(with  $P(\varphi, y) = \log |y_1| + f_1(\tilde{\varphi}, y) + y_1 f_2(\varphi, y) + f_3(\varphi_1, y_1)$ ) admits an invariant torus  $\mathcal{T}$ .

Moreover, there exists a diffeomorphism  $\mathbf{T}^n \to \mathcal{T}$  close to the identity taking the flow  $\gamma^t$  of the perturbed system on  $\mathcal{T}$  to the linear flow on  $\mathbf{T}^n$  with frequency vector  $(\frac{k+\epsilon k'}{c}, \tilde{\omega})$ .

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## Global classification

Circle actions on *b*-surfaces:



## Further results on *b*-manifolds

- Delzant theorem and convexity for  $\mathbb{T}^k$ -actions (Guillemin-M.-Pires-Scott).
- Symplectic topological aspects (Frejlich-Martínez-M).
- Quantization of *b*-symplectic manifolds (Guillemin- M.-Weitsman).
- What about  $b^n$ -symplectic manifolds? Guillemin-M.-Weitsman



#### Theorem (Guillemin-M.-Weitsman)

Given a  $b^m$ -symplectic structure  $\omega$  on a compact manifold  $(M^{2n}, Z)$ :

- If m = 2k, there exists a family of symplectic forms  $\omega_{\epsilon}$  which coincide with the  $b^m$ -symplectic form  $\omega$  outside an  $\epsilon$ -neighbourhood of Z and for which the family of bivector fields  $(\omega_{\epsilon})^{-1}$  converges in the  $C^{2k-1}$ -topology to the Poisson structure  $\omega^{-1}$  as  $\epsilon \to 0$ .
- If m = 2k + 1, there exists a family of folded symplectic forms ω<sub>ε</sub> which coincide with the b<sup>m</sup>-symplectic form ω outside an ε-neighbourhood of Z.

# Deblogging $b^{2k}$ -symplectic structures

$$\omega = \frac{dx}{x^{2k}} \wedge \left(\sum_{i=0}^{2k-1} \alpha_i x^i\right) + \beta \tag{4}$$

• Let  $f \in \mathcal{C}^{\infty}(\mathbb{R})$  be an odd smooth function satisfying f'(x) > 0 for all  $x \in [-1, 1]$ ,



and satisfying

$$f(x) = \begin{cases} \frac{-1}{(2k-1)x^{2k-1}} - 2 & \text{for } x < -1\\ \frac{-1}{(2k-1)x^{2k-1}} + 2 & \text{for } x > 1 \end{cases}$$

Eva Miranda (UPC)

**b-Symplectic manifolds** 

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# Deblogging $b^{2k}$ -symplectic structures

Scaling:

$$f_{\epsilon}(x) := \frac{1}{\epsilon^{2k-1}} f\left(\frac{x}{\epsilon}\right).$$
(5)

Outside the interval  $\left[-\epsilon,\epsilon\right]$  ,

$$f_{\epsilon}(x) = \begin{cases} \frac{-1}{(2k-1)x^{2k-1}} - \frac{2}{\epsilon^{2k-1}} & \text{for} \quad x < -\epsilon\\ \frac{-1}{(2k-1)x^{2k-1}} + \frac{2}{\epsilon^{2k-1}} & \text{for} \quad x > \epsilon \end{cases}$$

• Replace  $\frac{dx}{x^{2k}}$  by  $df_{\epsilon}$  to obtain

$$\omega_{\epsilon} = df_{\epsilon} \wedge (\sum_{i=0}^{2k-1} \alpha_i x^i) + \beta$$

which is symplectic.

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# Applications of deblogging

• Convexity for  $\mathbb{T}^k$ -actions.

- Delzant theorem and Delzant-type theorem for semitoric systems (bolytopes).
- Applications to KAM.
- Periodic orbits of problems in celestial mechanics and applications to stability (joint with Roisin Braddell, Amadeu Delshams, Cédric Oms and Arnau Planas).

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