MECHANICS ON GRADED BUNDLES

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Literature

The talk is based on some ideas of W. M. Tulczyjew and my collaboration with A. Bruce, K. Grabowska, and M. Rotkiewicz:

- Grabowski-Rotkiewicz, J. Geom. Phys. 62 (2012), 21–36.
- Bruce-Grabowska-Grabowski, J. Phys. A 48 (2015), 205203 (32pp).
- Bruce-Grabowska-Grabowski, *SIGMA* 11 (2015), 090, (25pp).
- Bruce-Grabowska-Grabowski, J. Geom. Phys. 101 (2016), 71–99.

• A vector bundle is a locally trivial fibration $\tau: E \to M$ which, locally over $U \subset M$, reads $\tau^{-1}(U) \simeq U \times \mathbb{R}^n$ and admits an atlas in which local trivializations transform linearly in fibers

$$U \cap V \times \mathbb{R}^n \ni (x, y) \mapsto (x, A(x)y) \in U \cap V \times \mathbb{R}^n$$

 $A(x) \in \mathrm{GL}(n,\mathbb{R}).$

- The latter property can also be expressed in the terms of the gradation in which base coordinates x have degrees 0 and 'linear coordinates' y have degree 1. Linearity in y is now equivalent to the fact that changes of coordinates respect the degrees.
- Morphisms in the category of vector bundles are represented by commutative diagram of smooth maps



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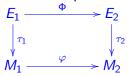


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$$U \cap V \times \mathbb{R}^n \ni (x, y) \mapsto (x, A(x, y)) \in U \cap V \times \mathbb{R}^n$$

- One can show that in this case A(x, y) must be polynomial in fiber coordinates, i.e. any graded bundle is a polynomial bundle.
- As these polynomials need not to be linear, graded bundles do not have, in general, vector space structure in fibers. For instance, if $(y,z) \in \mathbb{R}^2$ are coordinates of degrees 1,2, respectively, then the map $(y,z) \mapsto (y,z+y^2)$ is a diffeomorphism preserving the degrees, but it is nonlinear.
- If all $w_i \leq r$, we say that the graded bundle is of degree r.

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- Vector bundles are just graded bundles of degree 1.
- Canonical example: $T^kM \to M$ is a graded bundle of degree k with canonical coordinates $(x, \dot{x}, \ddot{x}, \ddot{x}, \dots)$ of degrees 0, 1, 2, 3, etc.

$$\begin{aligned} x'^{A} &= x'^{A}(x) \\ \dot{x}'^{A} &= \frac{\partial x'^{A}}{\partial x^{B}}(x)\dot{x}^{B} \\ \ddot{x}'^{A} &= \frac{\partial x'^{A}}{\partial x^{B}}(x)\ddot{x}^{B} + \frac{\partial^{2}x'^{A}}{\partial x^{B}\partial x^{C}}(x)\dot{x}^{B}\dot{x}^{C} \,. \end{aligned}$$

• Graded bundles F_k of degree k admit, like jet bundles, a tower of affine fibrations by reductions to coordinates of lower degrees

$$F_k \xrightarrow{\tau^k} F_{k-1} \xrightarrow{\tau^{k-1}} \cdots \xrightarrow{\tau^3} F_2 \xrightarrow{\tau^2} F_1 \xrightarrow{\tau^1} F_0 = M$$

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$$\nabla_F = \sum_a w_a y^a \partial_{y^a}.$$

- The flow of the weight vector field extends to a smooth action $\mathbb{R} \ni t \mapsto h_t$ of multiplicative reals on F, $h_t(x^\mu, y^a) = (x^\mu, t^{w_a}y^a)$. Such an action $h: \mathbb{R} \times F \to F$, $h_t \circ h_s = h_{ts}$, we will call a homogeneity structure.
- A function $f: F \to \mathbb{R}$ is called homogeneous of degree (weight) k if $\nabla_F(f) = k f$, or equivalently $f(h_t(x)) = t^k f(x)$.
- Note that for graded bundles only non-negative integer degrees of homogeneity are allowed. This is not true for more general 'graded manifolds': for F=(0,1), with the coordinate x of degree 1, the function x^a is homogeneous of degree a for all $a \in \mathbb{R}$.

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Morphisms of two homogeneity structures (F^i, h^i) , i=1,2, are defined as smooth maps $\Phi: F^1 \to F^2$ intertwining the \mathbb{R} -actions: $\Phi \circ h^1_t = h^2_t \circ \Phi$. Consequently, a homogeneity substructure is a smooth submanifold S invariant with respect to h, $h_t(S) \subset S$.

The fundamental fact (cf. [Grabowski-Rotkiewicz]) says that graded bundles and homogeneity structures are in fact equivalent concepts. There is namely a canonical isomorphism of the category of graded bundles and the category of homogeneity structures. This is because any manifold equipped with a homogeneity structure admits an atlas consisting of homogeneous functions.

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- We can extend the concept of a double vector bundle of Pradines and Mackenzie to double graded bundles.
- However, thanks to the simple description in terms of a homogeneity structure, the categorial and 'diagrammatic' definition can be substantially simplified.
- As two graded bundle structure on the same manifold are just two homogeneity structures, the obvious concept of compatibility leads to the following: A double graded bundle is a manifold equipped with two homogeneity structures h^1 , h^2 which are compatible in the sense that

$$h^1_t \circ h^2_s = h^2_s \circ h^1_t \quad ext{for all } s,t \in \mathbb{R} \,.$$

 For vector bundles this is equivalent to the concept of a double vector bundle invented and studied by Pradines and Mackenzie, and can be extended to n-fold graded bundles in the obvious way:

$$h_t^j \circ h_s^j = h_s^j \circ h_t^j$$
 for all $s, t \in \mathbb{R}$ and $i, j = 1, \dots, n$.

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$$h^1_t \circ h^2_s = h^2_s \circ h^1_t \quad ext{for all } s,t \in \mathbb{R} \,.$$

 For vector bundles this is equivalent to the concept of a double vector bundle invented and studied by Pradines and Mackenzie, and can be extended to n-fold graded bundles in the obvious way:

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 for all $s, t \in \mathbb{R}$ and $i, j = 1, \dots, n$.

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- Lifts. If $\tau: F \to M$ is a graded bundle of degree k, then TF and T^*F carry canonical double graded bundle structure: one is the obvious vector bundle, the other is of degree k.
- The above examples are double graded bundle whose one structure is linear. We will call such structures GrL-bundles.
- There are also lifts of graded structures on F to T^rF .
- In particular, if τ : E → M is a vector bundle, then TE and T*E are double vector bundles. The latter is isomorphic with T*E* (Tulczyjew, Mackenzie & Xu), with an isomorphism

$$\mathcal{R}_E:\mathsf{T}^*E^*\to\mathsf{T}^*E$$
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Since a linear Poisson structure on E* yields a map T*E* → TE*,
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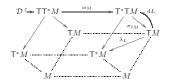
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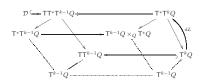


Motivation - higher order mechanics

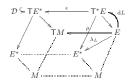
First order Lagrangian mechanics



k-th order Lagrangian mechanics



Reduction w.r.t. symmetry



reduced ...



Any $\mathcal{D} \subset \mathsf{TN}$ can be viewed as implicit dynamics whose solutions are curves $\gamma : \mathbb{R} \to \mathsf{N}$ s.t. $\dot{\gamma} \in \mathcal{D}$. For the lagrangian phase equations:

M - positions, TM - (kinematic) configurations, $L:TM \to \mathbb{R}$ - Lagrangian T^*M - phase space

$$\mathcal{D} = \varepsilon_M(\mathsf{d}L(\mathsf{T}M))) = \mathcal{T}L(\mathsf{T}M)\,,$$

the image of the Tulczyjew differential TL, is the phase dynamics

$$\mathcal{D} = \left\{ (x, p, \dot{x}, \dot{p}) : \quad p = \frac{\partial L}{\partial \dot{x}}, \quad \dot{p} = \frac{\partial L}{\partial x} \right\}$$

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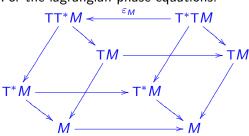
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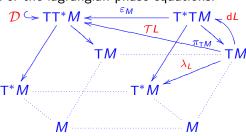
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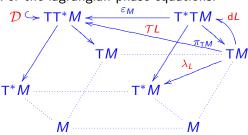
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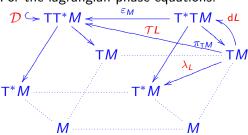
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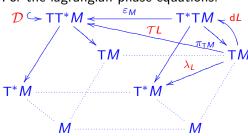
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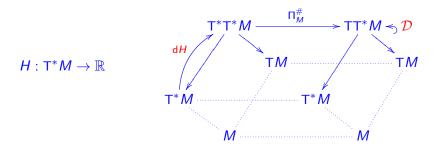


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The Tulczyjew triple - Hamiltonian side

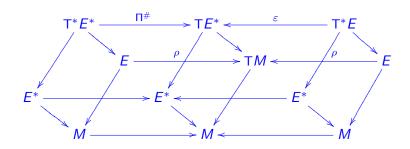


$$\mathcal{D} = \Pi_M^{\#}(dH(T^*M))$$

$$\mathcal{D} = \left\{ (x, p, \dot{x}, \dot{p}) : \dot{p} = -\frac{\partial H}{\partial x}, \dot{x} = \frac{\partial H}{\partial p} \right\},$$

whence the Hamilton equations.





$$H: E^* \longrightarrow \mathbb{R}$$

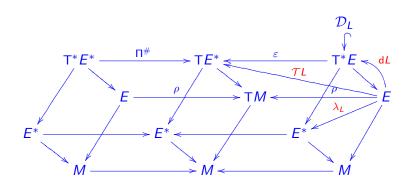
$$\mathcal{D}_H \subset \mathsf{T}^*E^*$$

$$\mathcal{D} = \mathcal{T}L(E)$$

$$\mathcal{D} = \Pi^\#(\mathsf{d} H(E^*))$$

$$L: E \longrightarrow \mathbb{R}$$

$$\mathcal{D}_L \subset \mathsf{T}^*E$$



$$H: E^* \longrightarrow \mathbb{R}$$

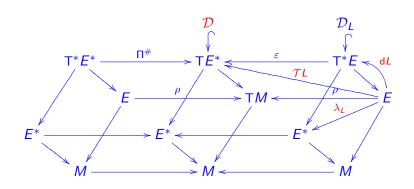
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$$\textit{L}:\textit{E}\longrightarrow\mathbb{R}$$

$$\mathcal{D}_L \subset \mathsf{T}^*E$$



$$H: E^* \longrightarrow \mathbb{R}$$

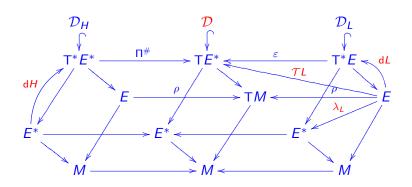
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$$L: E \longrightarrow \mathbb{R}$$

$$\mathcal{D}_L \subset \mathsf{T}^*E$$



$$H: E^* \longrightarrow \mathbb{R}$$

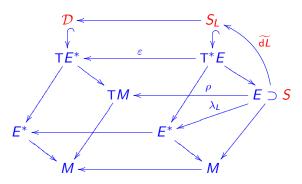
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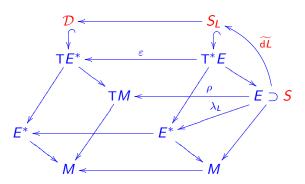
$$\mathcal{D}_H\subset \mathsf{T}^*E^*$$

$$\mathcal{D} = \Pi^{\#}(\mathsf{d}H(E^*))$$

$$\mathcal{D}_L\subset \mathsf{T}^*E$$

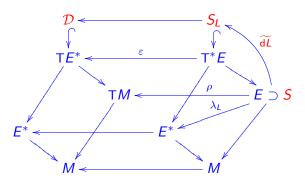


$$S_L = \{ \alpha_e \in \mathsf{T}_e^* E : e \in S \text{ and } \langle \alpha_e, v_e \rangle = \mathsf{d}L(v_e) \text{ for every } v_e \in \mathsf{T}_e S \}.$$



where S_I is the lagrangian submanifold in T^*E induced by the Lagrangian on the constraint S, and $dL: S \to T^*E$ is the corresponding relation,

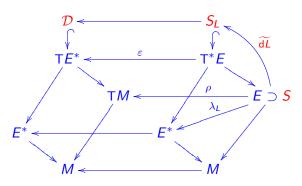
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Higher order Lagrangians

The mechanics with a higher order Lagrangian $L: \mathsf{T}^k Q \to \mathbb{R}$ is traditionally constructed as a vakonomic mechanics, thanks to the canonical embedding of the higher tangent bundle $\mathsf{T}^k Q$ into the tangent bundle $\mathsf{T}^{K-1} Q$ as an affine subbundle of holonomic vectors:

$$\left(q, \dot{q}, \ddot{q}, \dots, {k-1 \choose q}, {k \choose q} \right) \mapsto \left(q, \dot{q}, \ddot{q}, \dots, {k-1 \choose q}, \dot{q}, \ddot{q}, \dots, {k-1 \choose q}, {k \choose q} \right).$$

Thus we work with the standard Tulczyjew triple for TM, where $M = \mathsf{T}^{k-1}Q$, with the presence of vakonomic constraint $\mathsf{T}^kQ \subset \mathsf{TT}^{k-1}Q$.

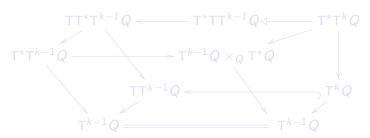


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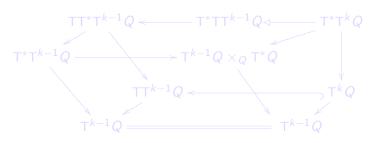
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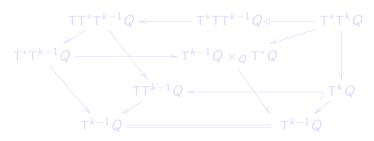
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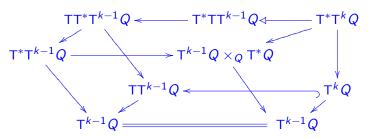
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This leads to the higher Euler-Lagrange equations in the traditional form:

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viewed as a vector bundle over $A^{k-1}(\mathcal{G})$ with respect to the obvious projection of part Z onto $A^{k-1}(\mathcal{G})$. Here, $\rho: A(\mathcal{G}) \to TM$ is the standard anchor of the Lie algebroid and $\tau: A^{k-1}(\mathcal{G}) \to M$ is the obvious projection. Moreover, the above bundle is canonically a weighted Lie algebroid. A Lie

Moreover, the above bundle is canonically a weighted Lie algebroid, a Lie algebroid prolongation in the sense of Popescu and Martínez.

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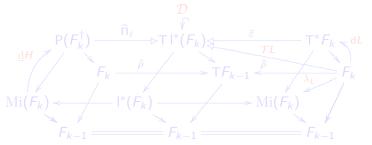
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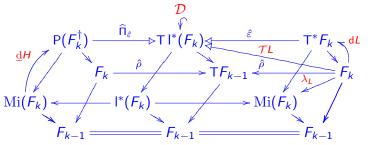
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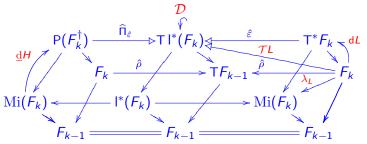
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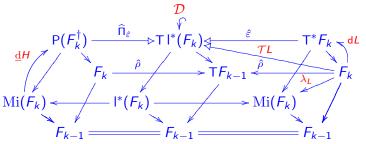


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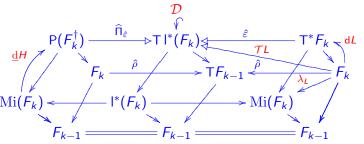
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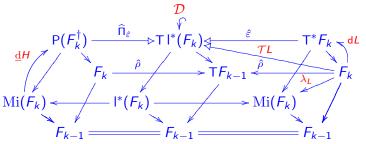
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A weighted Lie algebroid on $I(F_k)$ gives the Tulczyjew triple



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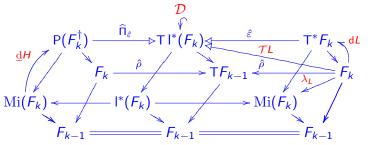
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Lagrangian framework for graded bundles

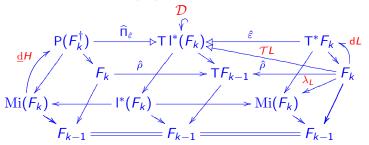
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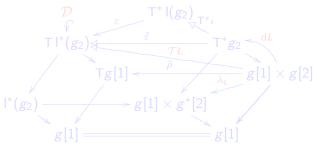
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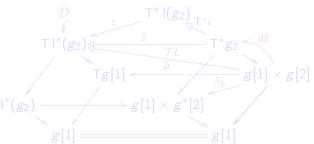
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What replaces Lie algebroids in this version of higher Lagrangian theory are linearizations of graded bundles equipped with weighted Lie algebroid structures (weighted Lie algebroids on symmetric GrL-bundles).

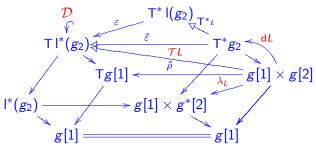
CSIC, 01/09/2016



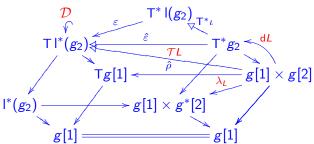
Let g be a Lie algebra and put $F_2 = g_2 = g[1] \times g[2]$, with coordinates (x^i, z^j) on g_2 and coordinates (x^i, y^j, z^k) on $I(g_2) = g[1] \times g[1] \times g[2]$. The vector bundle projection is $\tau(x, y, z) = x$ and the corresponding diagram looks like



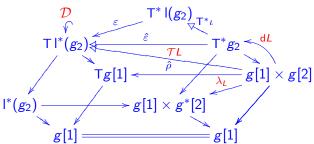
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so $\hat{\varepsilon}$ relates $(x, z, \alpha + \beta, \gamma)$ with $(x, \beta, \gamma, z, \operatorname{ad}_x^* \beta, \alpha)$.

Given a Lagrangian $L: g_2 \to \mathbb{R}$, the Tulczyjew differential relation $\mathcal{T}L: g_2 \to \mathsf{TI}^*(g_2)$ therefore reads

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Hence, for the phase dynamics

$$z = \dot{x}$$
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These equations are second order and induce the Euler-Lagrange equations on g which are of order 3:

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For instance, the 'free' Lagrangian $L(x,z) = \frac{1}{2} \sum_i I_i(z^i)^2$ induces the equations on $g(c_{ii}^k)$ are structure constants, no summation convention):

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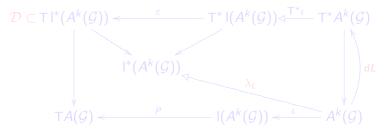
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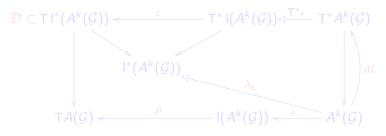


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Note that we deal with reductions: in the case $\mathcal G$ is a Lie group,

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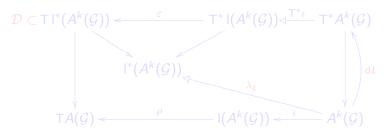


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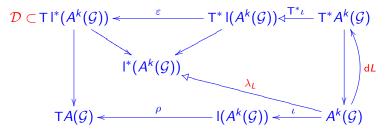


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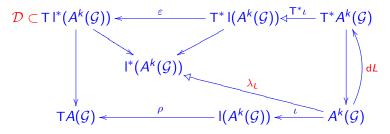


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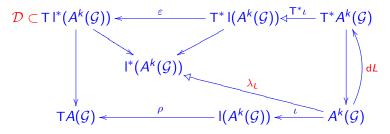


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$$(k-1)\pi_b^2 = \frac{\partial L}{\partial y_{k-1}^b} - \frac{1}{k} \frac{d}{dt} \left(\frac{\partial L}{\partial y_k^b} \right),$$

$$\vdots$$

$$\pi_d^k = \frac{\partial L}{\partial y_1^d} - \frac{1}{2!} \frac{d}{dt} \left(\frac{\partial L}{\partial y_2^d} \right) + \frac{1}{3!} \frac{d^2}{dt^2} \left(\frac{\partial L}{\partial y_3^d} \right) - \cdots$$

$$+ (-1)^k \frac{1}{(k-1)!} \frac{d^{k-2}}{dt^{k-2}} \left(\frac{\partial L}{\partial y_{k-1}^d} \right) - (-1)^k \frac{1}{k!} \frac{d^{k-1}}{dt^{k-1}} \left(\frac{\partial L}{\partial y_k^d} \right)$$

For instance, using x^A as base coordinates, and y^a as fibre coordinates of

$$k\pi_{a}^{1} = \frac{\partial L}{\partial y_{k}^{a}},$$

$$(k-1)\pi_{b}^{2} = \frac{\partial L}{\partial y_{k-1}^{b}} - \frac{1}{k} \frac{d}{dt} \left(\frac{\partial L}{\partial y_{k}^{b}} \right),$$

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For instance, using x^A as base coordinates, and y_i^a as fibre coordinates of degree i = 1, ..., k in A^k , extended by the appropriate momenta π^j_k of degree j = 1, ..., k in $I^*(A^k)$, we get the equations for the Legendre

$$k\pi_{a}^{1} = \frac{\partial L}{\partial y_{k}^{a}},$$

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For instance, using x^A as base coordinates, and y_i^a as fibre coordinates of degree i = 1, ..., k in A^k , extended by the appropriate momenta π^j of degree i = 1, ..., k in $I^*(A^k)$, we get the equations for the Legendre relation in the form (no Lie algebroid structure appears!):

$$k\pi_{a}^{1} = \frac{\partial L}{\partial y_{k}^{a}},$$

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$$\begin{split} k\pi_{a}^{1} &= \frac{\partial L}{\partial y_{k}^{a}}, \\ (k-1)\pi_{b}^{2} &= \frac{\partial L}{\partial y_{k-1}^{b}} - \frac{1}{k} \frac{d}{dt} \left(\frac{\partial L}{\partial y_{k}^{b}} \right), \\ \vdots \\ \pi_{d}^{k} &= \frac{\partial L}{\partial y_{1}^{d}} - \frac{1}{2!} \frac{d}{dt} \left(\frac{\partial L}{\partial y_{2}^{d}} \right) + \frac{1}{3!} \frac{d^{2}}{dt^{2}} \left(\frac{\partial L}{\partial y_{3}^{d}} \right) - \cdots \\ + (-1)^{k} \frac{1}{(k-1)!} \frac{d^{k-2}}{dt^{k-2}} \left(\frac{\partial L}{\partial y_{k-1}^{d}} \right) - (-1)^{k} \frac{1}{k!} \frac{d^{k-1}}{dt^{k-1}} \left(\frac{\partial L}{\partial y_{k}^{d}} \right) \end{split}$$

which we recognise as the Jacobi-Ostrogradski momenta.

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$$\frac{d}{dt}\pi_a^k = \rho_a^A(x)\frac{\partial L}{\partial x^A} + y_1^b C_{ba}^c(x)\pi_c^k \,,$$

$$\rho_a^A(x)\frac{\partial L}{\partial x^A} = \left(\delta_a^c \frac{d}{dt} - y_1^b C_{ba}^c(x)\right) \left(\frac{\partial L}{\partial y_1^c} - \frac{1}{2!} \frac{d}{dt} \left(\frac{\partial L}{\partial y_2^c}\right) \cdots - (-1)^k \frac{1}{k!} \frac{d^{k-1}}{dt^{k-1}} \left(\frac{\partial L}{\partial y_k^c}\right)\right)$$

The remaining equation for the dynamics is

$$\frac{d}{dt}\pi_a^k = \rho_a^A(x)\frac{\partial L}{\partial x^A} + y_1^b C_{ba}^c(x)\pi_c^k,$$

where ρ_a^A and C_{ba}^c are structure functions of the Lie algebroid $A=A(\mathcal{G})$. The above equation can then be rewritten as

$$\rho_{a}^{A}(x)\frac{\partial L}{\partial x^{A}} = \delta_{a}^{c}\frac{d}{dt} - y_{1}^{b}C_{ba}^{c}(x)\left(\frac{\partial L}{\partial y_{1}^{c}} - \frac{1}{2!}\frac{d}{dt}\left(\frac{\partial L}{\partial y_{2}^{c}}\right) \cdots - (-1)^{k}\frac{1}{k!}\frac{d^{k-1}}{dt^{k-1}}\left(\frac{\partial L}{\partial y_{k}^{c}}\right)\right)$$

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THANK YOU FOR YOUR ATTENTION!